

Program

February 2017

Thursday 23th

Friday 24th

08:00	Registration	
08:30		Registration
08:30	Inauguration	
09:00	Total and the form of the second	Note that the state of the stat
	Trajectory tracking for quadrotors and small airplanes	Vision oriented UAV development
09:00	Rogelio Lozano Leal	José Luis Gordillo Moscoso
10:15	The National Center for Scientific	Monterrey Institute of Technology -
	Research	Campus Monterrey
	Total Energy Control for Unmanned	Pursuit-Evasion Problems with
10.15	Aerial Vehicles	Robots
10:15 11:30	Hugo Rodríguez Cortés	Rafael Eric Murrieta Cid
11.50	Center of Research and Advanced	Centro de Investigación en
	Studies (CINVESTAV)	Matemáticas (CIMAT) - Guanajuato
11:30 11:45	Coffee Break	
	BlueBear Systems - Delivery and	Robust and Efficient Visual SLAM
11:45	development of GPS denied solutions	Nobast and Emolent visual SEAN
13:00	into operational UAS Richard Bostock	Andrew Calway
	BlueBear Systems Research, UK	University of Bristol, UK
13:00	Bracecar systems research, or	
14:30	Lunch Time	
	Visual-based Planning under	
	Uncertainty for 3D Reconstruction	
14:30 15:45	Luis Enrique Sucar Succar	Demos
15:45	National Institute of Astrophysics,	
	Opitcs and Electronics (INAOE)	
15:45	Coffee	Break
16:00		
	Learning to Fly with Transfer and Reinforcement Learning	New Neural Network Models and their Training Algorithms and
	nemorecine Learning	Applications
16:00	Eduardo Morales Manzanares	Juan Humberto Sossa Azuela
17:15	National Institute of Astrophysics,	Research Centre in Computer
	Opitcs and Electronics (INAOE)	Science of the National Polytechnic
		Institute (IPN)
	The Game of Drones	Event-based collaborative control
17:15	Bernardino Castillo Toledo	for consensus of VTOL-UAVs
18:30	Center of Research and Advanced	José Fermi Guerrero Castellanos
	Studies (CINVESTAV) - Guadalajara	Faculty of Electronics at BUAP
18:30		
19:30	Brindis	Closure















